

# Industrial motor controller for brushed DC motors 24 VDC

# Design for output currents up to 3 A

**Control with the following functions:** 

- reversal of direction of rotation
- overcurrent shutdown
- overcurrent indication output
- adjustable current monitoring delay
- short circuit detection
- dynamic brake

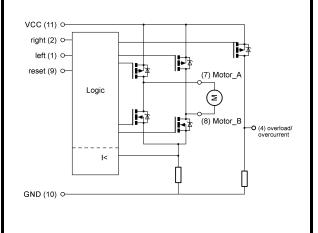
To snap onto the DIN rail EN 50022

Dynamic brake (Armature short circuit)

Unit width: 17,5 mm

 $\epsilon$ 





Type	M2-MWI-1-30

Article number		06.34.017
Operating data		
Nominal voltage	$U_nom$	24,0 VDC
Supply voltage	Vcc	18 30 VDC
Control inputs	U <sub>DI</sub>	24,0 VDC
Quiescent current typ	l <sub>0</sub>	50 mA
Technical data: load circuit	_	
Max. current / continuous load current	I <sub>max</sub> /I <sub>con</sub>	15 / 3 A * <sup>1</sup>
Short circuit current detection typ	Isc	40 A
Shut-down time after short circuit typ	t <sub>sc</sub>	100 μs
Power stage driver		MOS-FET
Other data		
Dimensions		17,5 x 70,4 x 85,0 mm
Connectors		screw terminal, pitch 5 mm
		cross section 0,2 – 2,5 mm <sup>2</sup>
Permissible ambient temperature	$T_{amb}$	-20 +60 °C
Temperature monitoring / overvoltage protection		yes / yes
Status indication: error / right / left		LED1 red / LED2 green / LED3 green
Overcurrent shut-off adjustable over DIP		250 1000 mA
Disable Time trimmer TR1 (CM-delay)		01s

<sup>\*1</sup> functional limited to 1A through overcurrent shut-off. 3A is valid while overcurrent shut-off is deactivated.

always on

# Datasheet M2-MWI-1-30 06.34.017

Other data	_	-
Installation orientation / Assembly		any / top-hat rail EN 50022
Installation place, typical		Switch cabinet
Storage temperature		-30 +85 °C
Permissible humidity		0 to 95 %, non-condensing
Weight		0,075 kg
Start up time		2 s
MTBF (SN29500, 40°C, rated load)		94,1 years
Hazardous substance norm		RoHS2
EMC interference immunity		EN 61326-1:2013-01 EN 61000-6-2:2005-08
EMC emitted interference, operation in industrial DC network		EN 61326-1:2013-01, Class A
EMC emitted interference, operation with power supply		EN 61326-1:2013-01, Class B
supply unit / power unit		KDR 120-24, Ott GmbH & Co. KG or comparable
Technical data: digital output overcurrent	_	
"Ready"		GND (4,7kΩ Pull-Down)
"Overcurrent"		Vcc
Current typ	I <sub>DO</sub>	700 [mA]
Short circuit-proof		Yes, self-limiting
Technical data: digital input		
High Signal typ.		U > 10 V
Low Signal typ.		U < 4 V
Impedance typ.	R <sub>DI</sub>	15 kΩ
Flammability	•	
Housing, terminals, printed circuit board		UL94V-0

# Starting behavior

After applying supply voltage, the module is ready for operation when the start up time has elapsed.

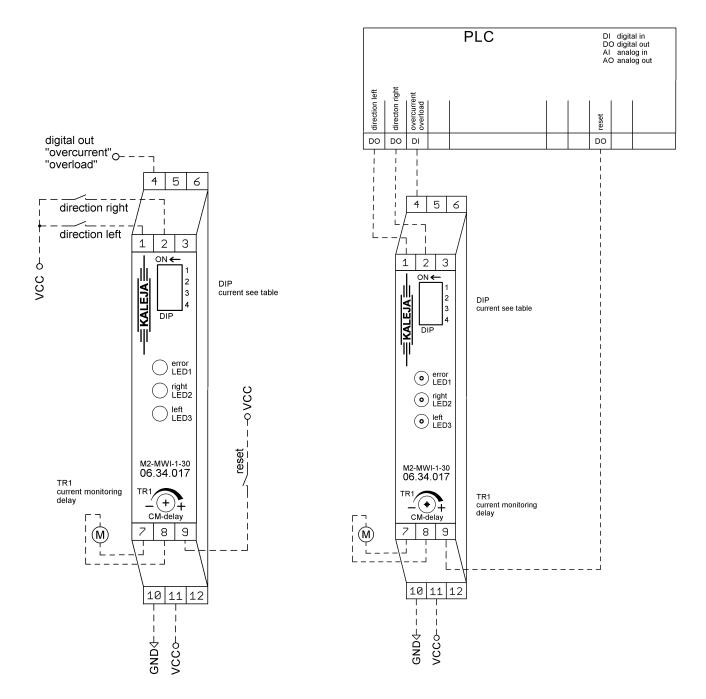
# Description

The module is a two quadrant motor control for use in industrial environments. It ensures the switching on and off, as well as the controlled driving of motors. Over a DIP switch the motor current limit value for the overcurrent shutdown is adjustable. The continuous load current form the module is 3A. A digital output reports if the module is in overcurrent shutdown mode. Current monitoring delay is adjustable over Trimmer TR1.

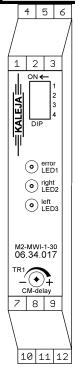
The module has two digital inputs to select the rotation directions and one digital input to reset the module if an overcurrent shutdown has appeared.

Typical application: Standard

Typical application: PLC



# Terminal diagram



4	5	6
digital output	Reserved	Reserved
"overcurrent"	NC	NC
High-aktiv		
1	2	3
digital input	digital input	Reserved
"direction left"	"direction right"	NC
(p- switch)	(p- switch)	
7	8	9
<b>7</b> Motor winding B	8 Motor winding A	9 digital input
		digital input
		digital input "reset"
Motor winding B	Motor winding A	digital input "reset" (p- switch)
Motor winding B	Motor winding A  11	digital input "reset" (p- switch) 12

# State table

direction "left" (1)	direction "right" (2)	Motor "B" (9)	Motor "A" (10)	Funktion
0	1	VCC	∏ GND	run right
1	0	∏ GND	VCC	run left
1	1	GND	GND	dyn. braking
0	0	GND	GND	dyn. braking

0 = off 1 = on x = don't care

# Function: overcurrent shut-off / overload

#### overcurrent shutdown:

The module has a DIP switch to adjust the current limit.

In case of an overcurrent shut-off the digital output (4) is set HIGH.

To reset the module set a HIGH Signal on digital input "reset" (9) or set both direction inputs(1 & 2) to low and start again in any direction.

# overload shutdown:

The module is internally protected with an overload shutdown. In case of rising of the motor current over the rated continuous load current the module switches of with a thermal safety function. After the shutdown the module is locked for a cooldown phase which is managed by the module.

In case of an overcurrent shut-off the digital output (4) is set HIGH.

To reset the module the cooldown phase must be over and both direction inputs (1 & 2) must set to low and start again in any direction.

# Function: setting the maximum motor current

The maximum motor current is adjusted via the DIP switch on the module.

The maximum permissible motor current is set via the DIP switches 1-4 (see table).

DIP1	DIP2	DIP3	DIP4	Max. current [A]
Off	Off	Off	Off	250
On	Off	Off	Off	300
Off	On	Off	Off	350
On	On	Off	Off	400
Off	Off	On	Off	450
On	Off	On	Off	500
Off	On	On	Off	550
On	On	On	Off	600
Off	Off	Off	On	650
On	Off	Off	On	700
Off	On	Off	On	750
On	On	Off	On	800
Off	Off	On	On	850
On	Off	On	On	900
Off	On	On	On	950
On	On	On	On	1000

# Function: dynamic brake

# Function: overload / short circuit detection

The motor always stops with dynamic brake while normal operation.

When the module detects overload or short circuit on the motor output, the motor switches off without dynamic braking. The motor can be restarted by means of a reset (9) or fresh setting of any input of direction of rotation.

# Function: disable overcurrent shutdown

# Function: current monitoring delay

The overcurrent shutdown is disabled while on digital input on terminal (9) a HIGH signal applied. The overload shutdown is still active.

The current monitoring delay is adjustable by trimmer TR1. After setting any direction of rotation input the overcurrent shutdown is disabled for the adjusted time.

# **Device status**

# Display elements

The module status is displayed via the LEDs on the module front plate.

Module errors are displayed as flashing sequences. The end of the sequence is indicated by a pause of 1 second.

The number of flashes indicates the error number.

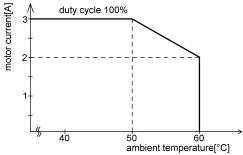
LED1	LED2	LED2	meaning
red	green	green	
Off	Off	Off	Module is
			operational
Off	On	Off	Run right
Off	Off	On	Run left
flashing	Off	On	Module error 1
			(see table)
			Occurred while
			running left
flashing	On	Off	Module error 1
			(see table)
			Occurred while
			running right
flashing	flashing	flashing	Internal Error

#### Module error 1

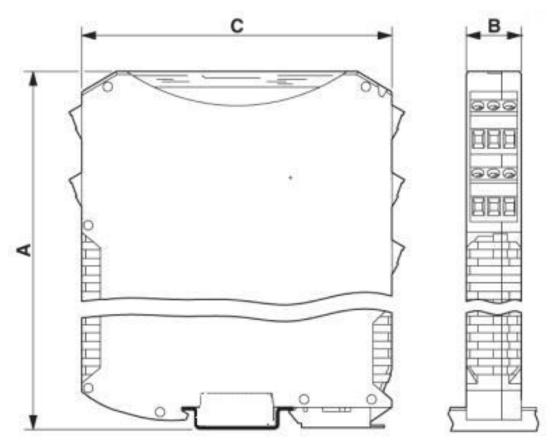
1	overcurrent
2	Over-temperature
3	short circuit detected
4	overvoltage
5	overload
6	Under-temperature
7	Low supply voltage
8	

# Temperature derating

At 100% duty cycle and aligned modules with 10mm spacing the following diagram is valid.



# Dimensional drawing



A = 70,4 mm; B = 17,5 mm; C = 85 mm

# Safety notes

## Maximum operational data

The maximum operating data must not be exceeded.

#### Installation

The installation and start-up must be performed by specialist personnel exclusively.

All affected components must be disconnected from the mains.

#### Start-up

For the first start-up, the motor should be operated without load.

# Risk of death

Do not touch live parts after switching on!

The assembly must be operated exclusively on safety extra-low voltage. With operation on extra-low voltage (e.g. via autotransformer), death or injury can occur.

## Fire protection

The assembly must be installed in a switch cabinet, which is suitable as a fire protection enclosure.

The assembly must be safeguarded with a pre-fuse aligned with the nominal data.

## Field of application

The assembly may only be used as intended.

Other components must be checked for their approvals and regulations.

## Safety devices

An additional safety device must be used to bring the system into a safe state in case of a cable break, incorrect operation, failure of the control/controller unit.

#### **EMC / EMI**

The wiring must be done according to EMC / EMI standards. If necessary, shielded cables and EMC suppressors must be used for the connected consumer.

For operation in a public low-voltage distribution network, the module must be supplied with an approved AC adapter.

If the module is supplied with an AC adapter, other equipment, operated on the same power supply, must be suitable for use in industrial environments.

## Repairs

Repairs must be performed by authorised persons exclusively. With unauthorised opening,

the warranty cover is voided and this may also result in danger for the user and for the system.

#### Maintenance

The assembly is wear-free by design.

For modules **with** cooling openings free air circulation must be checked at the cooling openings or on the housing at regular intervals. If necessary, the cooling holes / the housing must be cleaned.

Good ventilation must be ensured.

# contact details



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