KALEJA GmbH D-73553 Alfdorf

Motor-speed control for brush sticking direct current motor 12VDC.

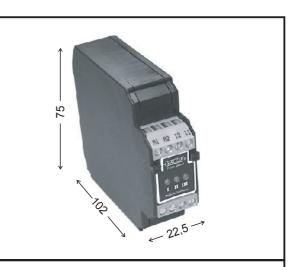
Implementation for switching current up to 5A. With speed control, starting ramp. Change of rotation.

To snap onto DIN - rail EN 50022 and EN 50035.

Construction width: 22,5mm

obsolete product consider 06.34.006 instead

Art. - No.



Rated voltage: 12VDC

06 04 019

Short designation / type Rated Voltage: Maxi-MR-5-12

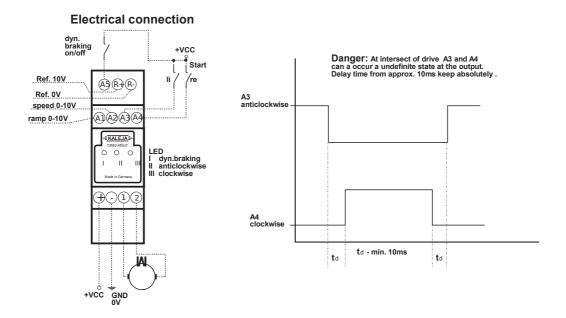
| Alti Hoi | 00.04.013 | | |
|---|------------------------|--|--|
| Technical data: input circuit | | | |
| Rated voltage / threshold voltage | 12 VDC | | |
| Range of rated voltage min. / max. | 10V to 15V DC | | |
| Input current during rated voltage | 10mA | | |
| Analogue input - range of voltage | 0V to 10VDC | | |
| Status indicator | LED 3mm yellow | | |
| Technical data: output circuit | MOS-FET | | |
| Range of switching voltage / motor voltage | 10V to 15V DC | | |
| Max. permanent load current | 6A | | |
| Current limitation till thermal switch-off come | 35A | | |
| Speed | 0V to VCC adjustable | | |
| Starting ramp | 50 . 4000ms adjustable | | |
| Power driver | MOS-FET | | |
| | | | |

| Other data | |
|--|------------------------------------|
| | |
| Ambient temperature range | -20°C to + 50°C |
| Absence of vibration a/r (10500Hz) | > 20 / 5 |
| Overload protection / short-circuit-proof / temperature monitoring | yes / yes / yes |
| DIN VDE-determinations | VDE 0110, 0160 in parts |
| Position of installation / mounting | can be snapped, addable |
| Mode of connection: screw terminal | single wire 4mm², fine wire 2,5mm² |
| Dimensions: W x D x H | 22,5mm x 75mm x 102mm |

Description

The Maxi-MR-5-12 module is a two-quadrant motor control system for 12VDC motors. It ensures safe switching ON/OFF and the controlled driving and braking of motors. The load can be short-circuited in OFF conditions wich result in dynamical braking.

Special features: Short-circuit protection, temperature protection, analog input for speed control and starting ramp.



Tab.1 Switching inputs and switching state at the outputs

| | Inputs | | | Outputs | |
|------------------------|--------------------|-----------------------|---------------------------|---------------------------|--------------|
| A3 Input/anticlockwise | A4 Input/clockwise | A5 Dyn.braking | 1 Motor connection | 2 Motor connection | Dyn. braking |
| 0 | 0 | 0 | 0V | 0V | on |
| 0 | 0 | ı | 0V | 0V | off |
| 0 | ı | х | +VCC | 0V | off |
| I | 0 | х | 0V | +VCC | off |

I = +VCC 0 =0V X = It doesn't matter

Tab2) Input A1 and ramp time

| Input A1 Ramp | Ramp time till 100% output voltage be reachedt |
|------------------|--|
| open | 50ms |
| 0V | 50ms |
| 10V | 4000ms |

Tab3) Input A2 and motor speed

| Input A2 Speed | Output voltage during 12VDC supply. |
|-------------------|--|
| open | 0V |
| <1V | ov |
| >1V to 10V | linear from 0V to 12V |